Linear Components



FAULHABER

Lead Screws and Options		Page
M1,2 x 0,25 x L1	Lead Screw	436
M1,6 x 0,35 x L1	Lead Screw	437
M2 x 0,2 x L1	Lead Screw	438
M3 x 0,5 x L1	Lead Screw	439
Options		440



Lead Screws and Options

Technical Information

Lead screws parameters

Resolution (travel/step)

A lead screw combined with a stepper motor can achieve a positioning with a resolution of 10µm.

The resolution of the position depends on the pitch and number of steps per revolution:

$$P = \frac{P_h}{n}$$

With P_h the pitch of the screw and n the number of steps per revolution of the motor.

Driving the motor with half-stepping or microstepping will improve the resolution up to a certain extent. The resolution must be balanced with another parameter: the precision.

Precision

The motor step angle accuracy is one parameter, together with the axial play between the nut and the lead screw, influencing the precision of the linear displacement. It varies between ± 3 and $\pm 10\%$ of a full step angle depending on the motor model (see line 9 on motor datasheet) and remains the same with microstepping. It is however not cumulative.

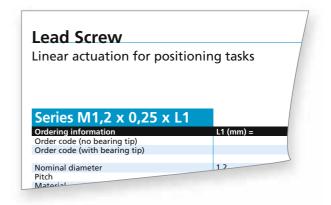
Axial play

An axial play up to 30µm is measured with optional nuts offered in this catalogue. However, it is possible to negate the axial play by implementing a preloading system in the design of the application (for instance with a spring mechanism).

The "zero" axial play between the lead screw and motor housing is ensured thanks to a preload of the motor ball bearings (in standard configuration: spring washer on rear ball bearing). An axial play up to 0.2 mm will occur if the axial load on the lead screw exceeds the ball bearing preload.

This does not cause any damage to the motor and is reversible. This occurs only while pulling on the shaft. On request, customization can overcome this limitation.

To avoid irreversibly damaging the motor, the maximum axial load should always remain under the maximal push force the motor can generated with a mounted lead screw.



Backdriving

Backdriving the motors while applying an axial load on the lead screws is impossible. The pitch vs. diameter ratio does not allow it.

Force vs speed curves

The force that a linear system can provide depends on the type of screw and stepper motor selected. Torque vs speed curves for each solution are provided in this catalogue. Those curves do already consider a 40% safety factor on the motor torque as well as a conservative lead screw efficiency in the calculation.

Tip for bearings

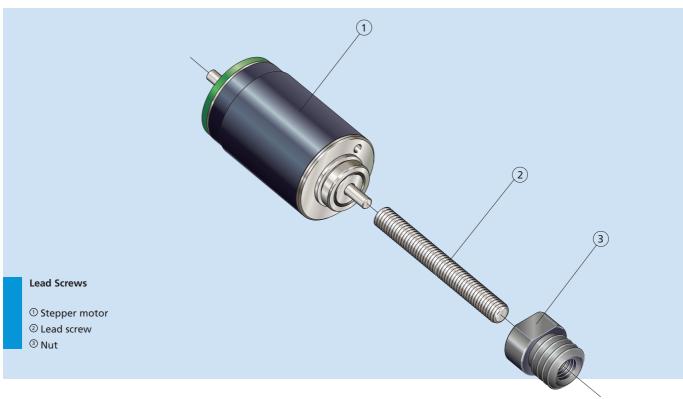
Ideally, the application should handle radial loads and the lead screw only axial loads. If it is not the case, it is possible to get lead screws with a tip suitable for bearing at its front end in order to handle radial loads. With this configuration, a special care to the alignment of the motor and bearing must be paid to not deteriorate the thrust force achievable. Optional mating ball bearings are available in the dedicated datasheet for options.

Nut

Optional nuts offered in this catalogue are shaped with a flat in order to prevent its rotations in the application. Alternatively, tapped holes on the application are a convenient solution since metric taps are readily available.



Lead Screws and Options



Features

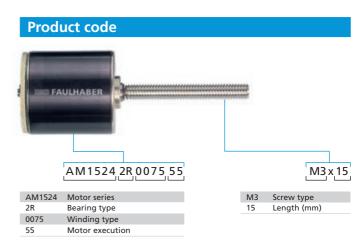
Stepper motors can be used for more than just a rotation. When combined with lead screws, they provide a high accuracy linear positioning system that provides the benefits of a stepper (open loop control, long life, high torque density, etc.).

The lead screws available on stepper motors are all based on metric dimensions (M1.2 up to M3) and specifically designed to be assembled with stepper motors. The technique used to produce the thread ensures a very high precision and consistency of quality. A large choice of standard lengths is available from stock and customization is possible on request.

Such a combination is ideal for any application such as requiring accurate linear movement or lens adjustment (zoom, focus), microscope stages or medical syringes.

Benefits

- Cost effective positioning drive without encoder
- High accuracy
- Wide range of lead screws available
- Short lead time for standard length
- Flexibility offered by optional nuts and ball bearings
- Custom length on request





Linear actuation for positioning tasks

For combination with **Stepper Motors**

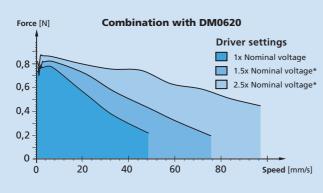
		_		
CHIOC	1 1			M 1
Series			6	

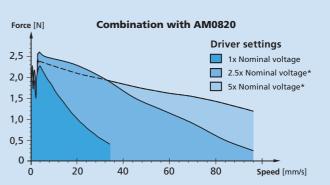
Ordering information	L1 (mm) =	7.5	15	Custom	
Order code (no bearing tip)		M1.2x7.5	M1.2x15	M1.2xL1*	
Order code (with bearing tip)		-	_	_	
Nominal diameter	1,2				mm
Pitch	0,25				mm
Material	Stainless steel				

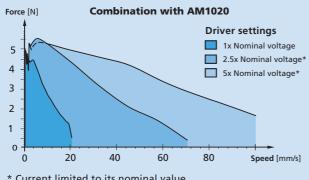
* For custom length, please inquire with your point of sales

For combination with Stepper Motors DM0620, AM0820, AM1020 Important notes

The thrust curves include already a safety factor for the use of the stepper motor. Please read the "Technical information" for a better understanding of the curves.

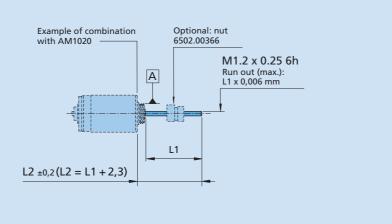






* Current limited to its nominal value

Dimensional drawing



M1,2 x 0,25 x L1



Linear actuation for positioning tasks

For combination with **Stepper Motors**

CHICK	11/1/1/2/1	- M
	$M1,6 \times 0$	_

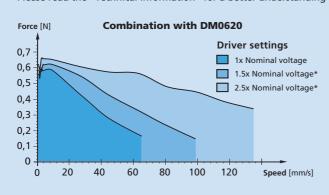
Ordering information	L1 (mm) =	7.5	15	25	Custom	
Order code (no bearing tip)		M1.6x7.5	M1.6x15	_	M1.6xL1*	
Order code (with bearing tip)		_	M1.6x15T	M1.6x25T	M1.6xL1*T	
Nominal diameter	1,6					mm
Pitch	0,35					mm
Material	Stainless steel					

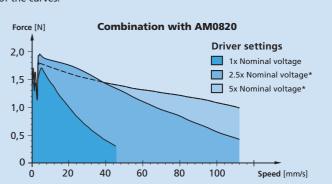
* For custom length, please inquire with your point of sales

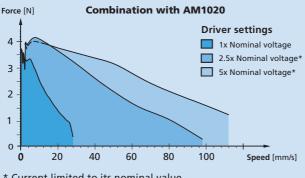
For combination with Stepper Motors DM0620, AM0820, AM1020

Important notes

The thrust curves include already a safety factor for the use of the stepper motor. Please read the "Technical information" for a better understanding of the curves.

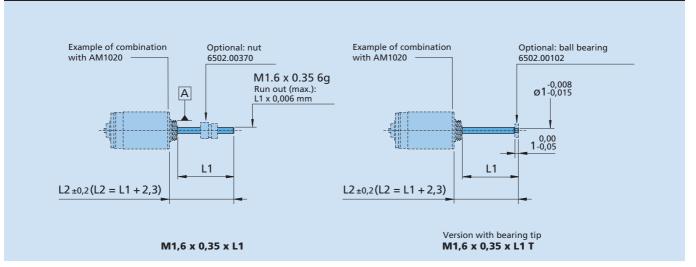






* Current limited to its nominal value

Dimensional drawing

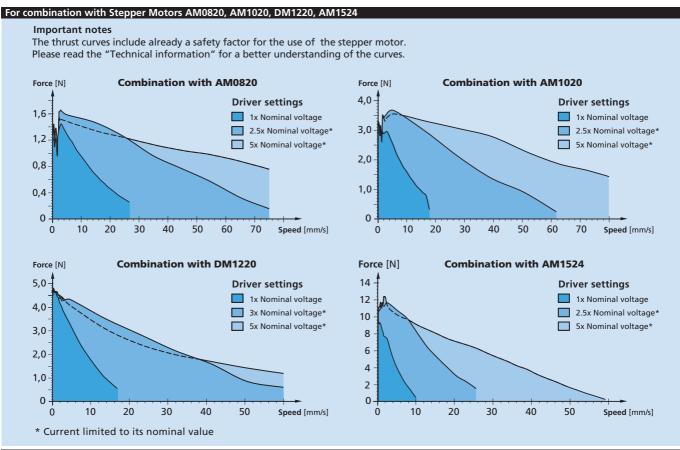


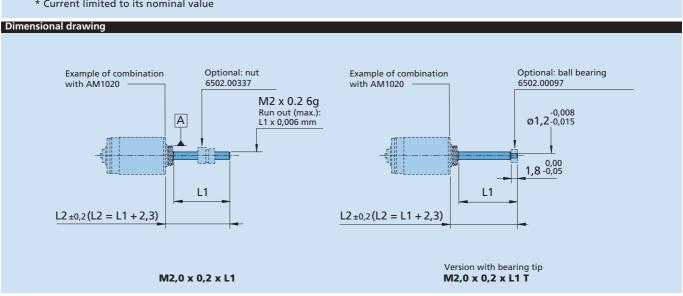


Linear actuation for positioning tasks

For combination with Stepper Motors

Series M2 x 0,2 x L1						
Ordering information	L1 (mm) =	15	25	28/30	Custom	
Order code (no bearing tip)		M2x15	M2x25	M2x30	M2xL1*	
Order code (with bearing tip)		M2x15T	M2x25T	M2x28T	M2xL1*T	
Nominal diameter	2,0					mm
Pitch	0,2					mm
Material	Stainless steel					
						•
* For custom length, please inquire with yo	our point of sales					



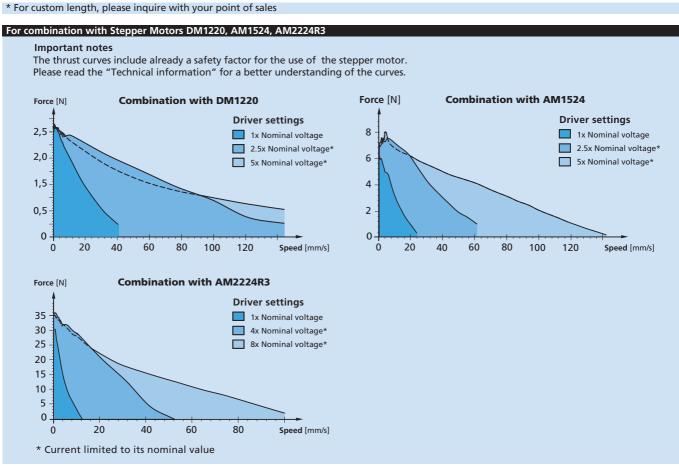


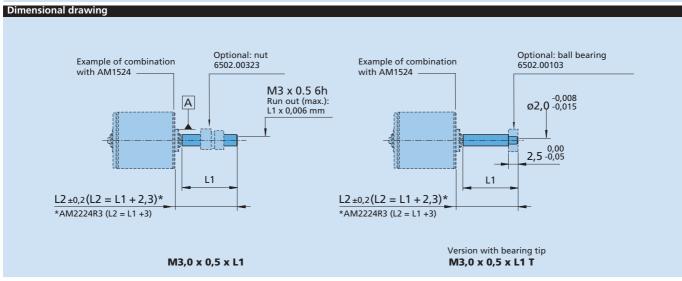


Linear actuation for positioning tasks

For combination with Stepper Motors

L1 (mm) =	15	25	50	Custom	
	M3x15	M3x25	_	M3xL1*	
	M3x15T	M3x25T	M3x50T	M3xL1*T	
3,0					mm
0,5					mm
Stainless steel					
	3,0 0,5	M3x15 M3x15T 3,0 0,5	M3x15 M3x25 M3x15T M3x25T 3,0 0,5	M3x15 M3x25 – M3x15T M3x25T M3x50T 3,0 0,5	M3x15 M3x25 - M3xL1* M3x15T M3x25T M3x50T M3xL1*T 3,0 0,5







Optional nuts and bearings

